



COURSE DESCRIPTION CARD - SYLLABUS

Course name

Numerical Methods and Simulation [S1AiR1>MNiS]

Course

Field of study

Automatic Control and Robotics

Year/Semester

1/2

Area of study (specialization)

–

Profile of study

practical

Level of study

first-cycle

Course offered in

polish

Form of study

full-time

Requirements

compulsory

Number of hours

Lecture

15

Laboratory classes

30

Other (e.g. online)

0

Tutorials

0

Projects/seminars

0

Number of credit points

4,00

Coordinators

dr inż. Janusz Pochmara

janusz.pochmara@put.poznan.pl

Lecturers

dr inż. Krzysztof Kolanowski

krzysztof.kolanowski@put.poznan.pl

dr inż. Piotr Kuwałek

piotr.kuwalek@put.poznan.pl

dr inż. Jarosław Majchrzak

jaroslaw.majchrzak@put.poznan.pl

dr inż. Paweł Parulski

pawel.parulski@put.poznan.pl

dr inż. Radosław Patelski

radoslaw.patelski@put.poznan.pl

dr inż. Janusz Pochmara

janusz.pochmara@put.poznan.pl

dr inż. Paulina Superczyńska

paulina.superczynska@put.poznan.pl

dr hab. Magdalena Szymkowiak

magdalena.szymkowiak@put.poznan.pl

Prerequisites

Knowledge of mathematical description of physical phenomena occurring in automation and robotics systems. Ability to model automation systems and manipulators. Programming using high level C ++, Java, and scripting Python, Matlab etc.

Course objective

Preparing students for using numerical skills in analysis and simulation of systems and processes of analysis in automation and robotics. The course discusses issues related to modeling and description of the phenomenon of growth in automation systems and applications as well as numerical methods of analysis of these systems

Course-related learning outcomes

Knowledge

Modeling methods and description of dynamic systems. Numerical implementation of dynamic models and processes. Numerical solving of equations describing linear and nonlinear systems

Skills

Modeling systems using state equations and simulation of automatics and robotics systems. Assessment of compliance of the numerical results obtained with actual results

Social competences

Understands the need and knows the possibilities of continuous training, raising professional, personal and social competences. Is aware of the need for a professional approach to technical issues and meticulous familiarity with the issues undertaken. He understands the need and the possibility of further transfer of acquired knowledge and skills

Methods for verifying learning outcomes and assessment criteria

Learning outcomes presented above are verified as follows:

In the field of laboratory exercises, verification of assumed learning outcomes is carried out by continuous assessment in each class (oral answers, laboratory reports), in addition by assessing acquired knowledge and skills through one or two tests in a semester.

In the field of laboratory exercises, verification of assumed learning outcomes is carried out by continuous assessment in each class (oral answers, reports), in addition by assessing acquired knowledge and skills through one or two tests in the semester.

Programme content

The lecture program includes the following topics:

Machine representation of numbers and numerical errors, definition and description of dynamic systems, state vector and state space, solving state equations. Methods of analysis of linear systems and processes, numerical solving of systems of linear equations, methods of solving differential equations: Euler, Heun, Taylor series, Runge-Kutta, Runge-Kutty-Fehlberg, methods of analysis of nonlinear systems and processes, numerical solving of systems of nonlinear equations and nonlinear equations differential.

Application and implementation of algorithms for the analysis of linear and non-linear systems and processes in electrical engineering, assessment of convergence of algorithms, stability and proper discretization of the methods used, analysis of the obtained numerical simulation results.

Laboratory exercises are conducted in the form of fifteen 2-hour meetings. Preparation for one meeting is subject to one topic. During classes, students solve received tasks using computers in the indicated virtual environment in the field of material presented in the lectures.

The curriculum includes:

Modeling and numerical implementation of linear and nonlinear static and dynamic systems.

Solving systems of linear and nonlinear equations.

Implementation and analysis of methods for solving Euler, Heun linear differential equations, Taylor series, Runge-Kutta, Runge-Kutty-Fehlberg.

Implementation and analysis of interpolation and extrapolation methods for solving nonlinear differential equations.

Application and implementation of algorithms for system analysis and automatic control processes

Evaluation of convergence of algorithms, stability and proper discretization of the methods used, analysis of the results obtained

Teaching methods

Teaching methods:

1. lecture: multimedia lecture with examples supported by explanations on the board
2. laboratories: numerical implementation and task analysis, discussion

Bibliography

Basic

1. John H. Mathews, Kurtis D. Fink, Numerical Methods using Matlab, Wydawnictwo Prentice Hall 1999r.
2. David Kincaid, Ward Cheney, Analiza numeryczna, Wydawnictwa Naukowo-Techniczne 2006r

Additional

1. Miedzianek M., Stepień S., Numeryczna analiza systemów dynamicznych w środowisku Matlab, PWSZ Leszno, 2011

Breakdown of average student's workload

	Hours	ECTS
Total workload	90	4,00
Classes requiring direct contact with the teacher	45	2,00
Student's own work (literature studies, preparation for laboratory classes/ tutorials, preparation for tests/exam, project preparation)	45	2,00